

The National High Performance Computing Workshop on Resilience

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Reliability Availability and Serviceability (RAS) Subsystems

- In this context
 - Systems Software used to monitor and control the platform
- To support of Application Resilience
 - Needs to be far more
- Current "true" RAS subsystem examples
 - Cray XT3/4/5 RAS subsystem
 - Blue Gene RAS subsystem
- Risk Areas
 - Hardware
 - Software



Three Laws of Robotics RAS Subsystems

(Somewhat Anthropomorphized) – Isaac Asimov

1. The RAS subsystem shall not injure the platform it serves or interfere with the main purpose of that platform.

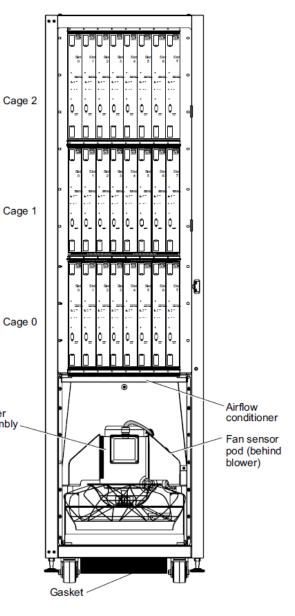
....ok well maybe there is only one.

- Out of Band (OOB) becomes more important.
- How do we monitor and control without affecting, or minimally affecting, the underlying platform?
 - Pretty simple if we don't do much
 - Gets harder as we try to satisfy resilience requirements
- To support Resilience we need to do MUCH more



RAS Subsystem is already a System

- For example
 - Red Storm (Cray XT4)
 - 135 (compute cabinets) * 3 (cages per cabinet) * 8 (slots per cage) * 1 (L0 per board) = 3240 L0's
- Additionally, one L1 per cabinet (135 L1's)
- One top-level System Management Workstation (SMW)
- Equivalent to a 3240+ node (disk-less) cluster
 - not counting the L1's
- * Jaguar: at ≈ 200 cabinets, 4800 L0's





Projecting into the Future

- 1 Peta-Flops delivered soon-ish
 - Pretty much the same numbers
- 10 Peta-Flops??
 - ≈500 (compute cabinets) * 3 (cages per cabinet) * 8 (Slots per cage) * 1 (L0 per board) = 12000
- Red Storm currently has 12960 compute nodes.
- Will we need a RAS sub-system for the RAS subsystem?
- Will hierarchical schemes break down?
- Failure rates have significant implications at these numbers!!



RAS for Resilience

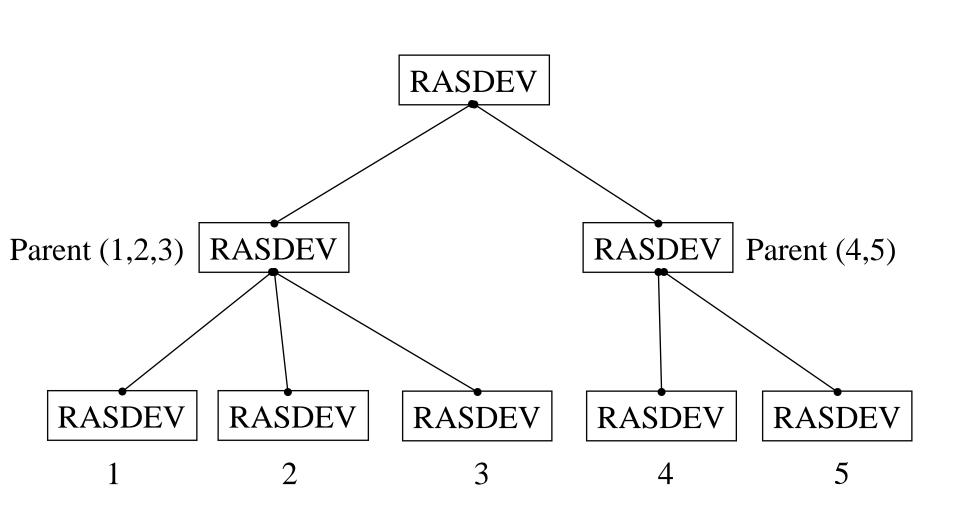
- Resilience research ASS/U/MES capable RAS subsystem
 - We do, what choice do we have?
- Reality of a RAS subsystem
 - What we THINK it provides
 - What it DOES provide
 - What we NEED it to provide
- Unfortunately these tend to be very different things....
 - In addition, differ depending on platform!
- We must close this gap.



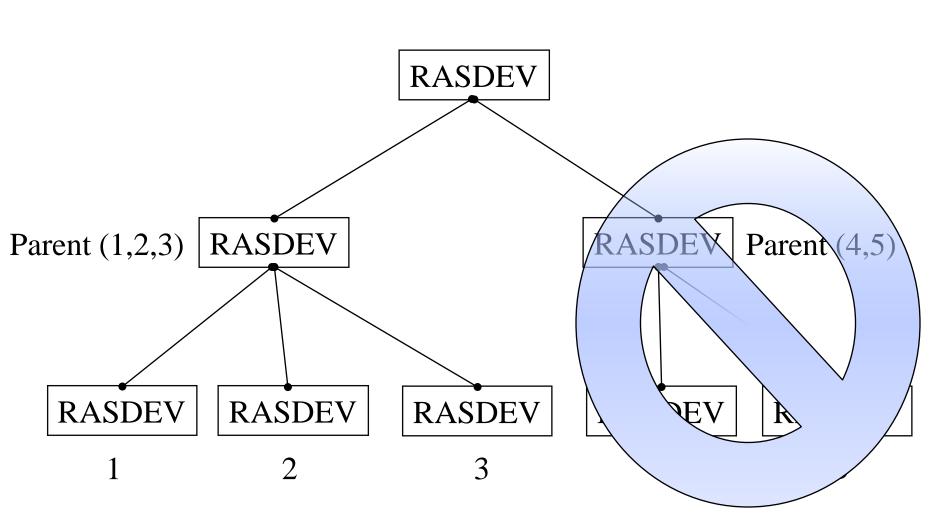
Mitigating challenges

- Configure hardware differently
 - For example, is one RAS node per board over-kill?
 - Maybe not as requirements increase to support Resilience
- Overlay Networks and other distributed systems concepts to deal with failures?
 - Dynamically re-organize network hierarchy
 - Dynamic role assumption
- Light Weight RAS message protocols?
- More intelligent RAS software?
 - Keep uninteresting things from propagating
 - What is uninteresting?

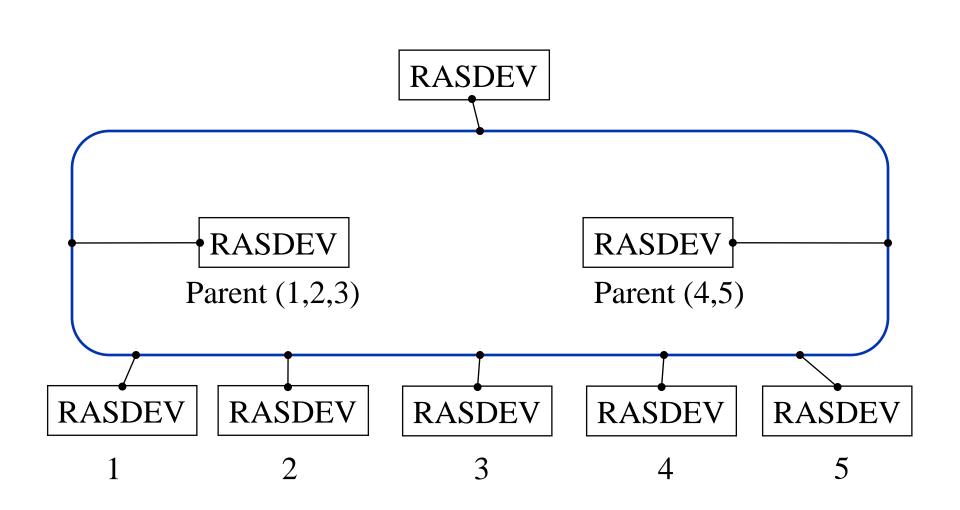




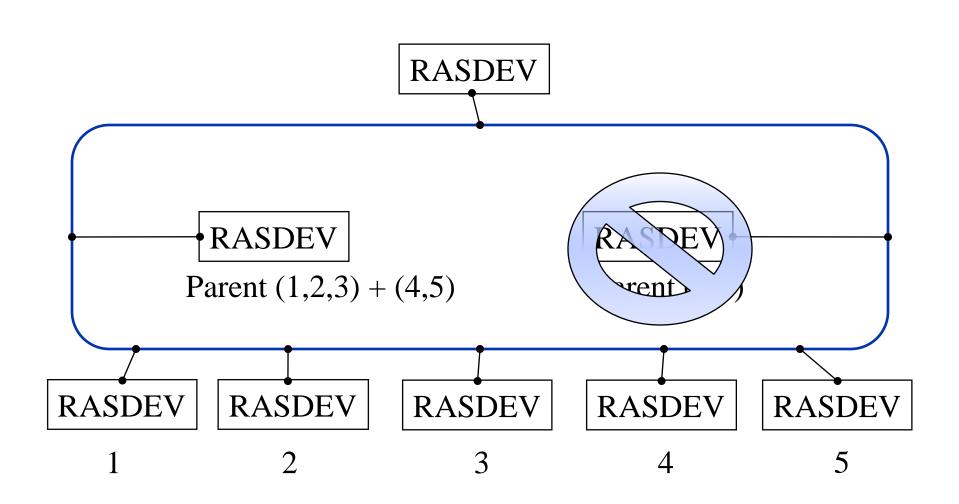














What Does Resilience Require?

- In a word, INFORMATION
 - System Centric
 - Node characteristics
 - Physical and Logical locality of node
 - Other component information
 - Status/State type information
 - Syslog-like data
 - Sensor data
 - Huge number and numerous types
 - Component states
 - Hardware AND Software components
 - Job layout
- Once we have it, we need to GET it!
- Numerous stakeholders



Areas we can IMPACT

RAS API

- Standard way to interface with RAS subsystem
 - Does not dictate underlying sub-system!
 - More likely to get vendor cooperation.
 - Subscription based, Query based, etc.
 - How we make sense out of INFORMATION
- Community researching resilience best equipped to define needs (from their perspective)
 - Other stakeholders must be involved
- Standardized Backend
 - With a complete API likely not necessary
 - Could be an area of commonality between vendors



Areas we can IMPACT (continued)

- RAS Communication Protocols
 - Possible wide applicability
 - University interest
 - At scale contributions
- Common RAS foundation
 - System Description Language
 - Promotes a Systems View of platform



Conclusions/Questions

- We can have impact in this area
 - We have had some already
- Value in collaboration, and developing a standard
 - Vendors hear the same requirement from everyone

